Polynomial Convexity of Simple Complex Shapes

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Background

We consider polynomially convex sets, a generalization of convex sets.

Definition. For any compact $Y \subset \mathbb{C}^n$, we define the polynomial hull of Y to be

$$Y^{\wedge} = \Big\{ x \in \mathbb{C}^n : |p(x)| \le \sup\{|p(y)| : y \in Y\} \text{ for all polynomials } p \Big\}.$$

We say Y is polynomially convex if $Y = Y^{\wedge}$.

In particular, a convex set is polynomially convex.



Our research focuses on the disjoint union the following objects:

- sphere = { $z \in \mathbb{C}^n : |z_1 a_1|^2 + ... + |z_n a_n|^2 \le r^2$ }
- polydisk = $\{z \in \mathbb{C}^n : |z_1 a_1| \le r_1, ..., |z_n a_n| \le r_n\}$
- generalized super-ellipsoid (GSE) = { $z \in \mathbb{C}^n : |z_1 a_1|^k + ... + |z_n a_n|^k \le r^k$ } for some exponent $k \ge 2$, which we call the degree of the GSE

Characterizing Polynomial Convexity in C

Theorem. A compact set $Y \subset \mathbb{C}$ is polynomially convex if and only if the complement $\mathbb{C} \setminus Y$ is connected.

- The forward direction follows from the maximum modulus principle.
- The reverse direction follows from a clever application of Runge's theorem.





Important Results from Kallin

Kallin's paper [1] forms the basis of our work, providing us with:

- A method for proving polynomial convexity of the disjoint union of several objects, called the separation lemma.
- A method for generating a counterexample to show the disjoint union of sevearl objects is not polynomially convex.

Using the Separation Lemma to Prove Polynomial Convexity

Separation Lemma. If $X_1, X_2 \subset \mathbb{C}^n$ compact and f is a polynomial such that $(f[X_1])^{\wedge} \cap (f[X_2])^{\wedge} = \emptyset$, then $(X_1 \cup X_2)^{\wedge} = X_1^{\wedge} \cup X_2^{\wedge}$.

Important Results from Kallin (continued)

Theorem (Kallin). The disjoint union of any three balls S_1, S_2, S_3 are polynomially convex in \mathbb{C}^n .

- Two balls are polynomially convex so it suffices to separate S_1 from S_2 and S_3 .
- Scale the balls such that the largest ball S_1 has radius 1.
- Choose coordinates and rotate the balls such that S_1 has center (0,0), S_2 has center $(\gamma, 0)$ with $\gamma \in \mathbb{C}$ and S_3 has center (α, β) with $\alpha, \beta \in \mathbb{R}$.
- The polynomial $f(z) = z_1^2 + z_2^2$ will separate S_1 from S_2 and S_3 .

Using the Maximum Modulus Principle to Find Counterexamples

Theorem (Kallin). There exists a collection of three disjoint polydisks that is not polynomially convex in \mathbb{C}^3 .

- Define a surface cut out by $z_1z_2 = 1, z_3(1 z_1) = 1$. On the surface, take the curves $|z_1| = M$, $|z_2| = M$, $|z_3| = M$ for some M > 2.
- Basic idea: the polynomial hull of the three curves contains the part of the surface bounded by the three curves. If we can fit three (disjoint) polydisks over each of the three curves, then their polynomial hull will also contain this section of the surface.



Projections of the three curves when M = 2.2. • The polydisks of radius M, centered at $\left(-M + \frac{1}{M}, 0, M + \frac{M}{M+1}\right)$ and $\left(M + 1 - \frac{M}{M+1}\right)$ $\frac{1}{M}$, $M + \frac{M}{M+1}$, 0) and $(0, -M + \frac{1}{M}, -M + \frac{1}{M+1})$ satisfy this condition.

Three Polydisks in \mathbb{C}^2

Theorem. The disjoint union of any three polydisks P_1, P_2, P_3 are polynomially convex in \mathbb{C}^2 .

- By the same argument as Kallin's three spheres, it suffices to separate one polydisk from the other two.
- Any two disjoint polydisks can intersect in at most one coordinate projection. (If they intersect in both projections, they are no longer disjoint.)



Question. If we could slowly stretch a sphere into a polydisk, at what point in this process would the intermediate shape become not polynomially convex?

To answer this, we came up with the idea of GSEs, noting that a GSE with k = 2is simply a sphere, and as $k \to \infty$, the GSE approaches a polydisk.

Theorem. When the degree $k \ge 18.121$, the disjoint union of three GSEs E_1, E_2, E_3 is not polynomially convex in \mathbb{C}^3 .



Despite being a natural generalization of convexity, much less is understood about the idea of polynomial convexity. As our research demonstrates, even simple shapes fail to admit intuitive solutions. In the future, some problems we would like to explore include:

- 18.121 are polynomially convex
- raising the dimension
- projective space

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[1] Eva Kallin Polynomial convexity: The three spheres problem



Three GSEs in \mathbb{C}^n

• We use Kallin's surface cut out by $z_1z_2 = 1, z_3(1 - z_1) = 1$, and on the surface, take the curves $|z_1| = M, |z_2| = M, |z_3| = M$ for some M > 2.

• We center E_1, E_2, E_3 at $(-M + \frac{1}{M}, 0, M + \frac{M}{M+1})$ and $(M + 1 - \frac{1}{M}, M + \frac{M}{M+1}, 0)$ and $(0, -M + \frac{1}{M}, -M + \frac{1}{M+1})$ respectively, with radii r_1, r_2, r_3 .

• Two GSEs cannot intersect, allowing us to bound the radii from above.

• E_1, E_2 and E_3 must contain the curves $|z_1| = M, |z_2| = M, |z_3| = M$, allowing us to bound the radii from below.

• The difference between our two bounds (which are in terms of *M* and *k*) must be positive in the worst case. Choose $M \approx 4$, then the condition holds $k \geq 18.121$.

A 3-real-dimensional analog of a GSE with k = 2, k = 19 and $k = \infty$.

Conclusion and Future Work

• Finding a separating polynomial to prove that three GSEs with degree 2 < k < k

• Using the Fubini-Study metric to show that $k \ge 18.121$ cannot be improved by

• Improving the bound of $k \ge 18.121$ by finding a more optimal surface and curves • Determining if four polydisks are polynomially convex in \mathbb{C}^2 using surfaces in

 Finding new techniques for proving and disproving polynomial convexity to tackle questions like the four spheres problem

Acknowledgements

References

In Alfred Aeppli, Eugenio Calabi, and Helmut Röhrl, editors, Proceedings of the Conference on Complex Analysis, pages 301–304, Berlin, Heidelberg, 1965. Springer Berlin Heidelberg

The proof arises from Runge's theorem.